

[Robótica] Canal de Juan Carlos Martín Castillo

General

1. [Canal Juan Carlos Martín Castillo](#)
2. [RAPID avanzado](#)
3. [Revista de Electricidad, Electrónica y Automática](#)

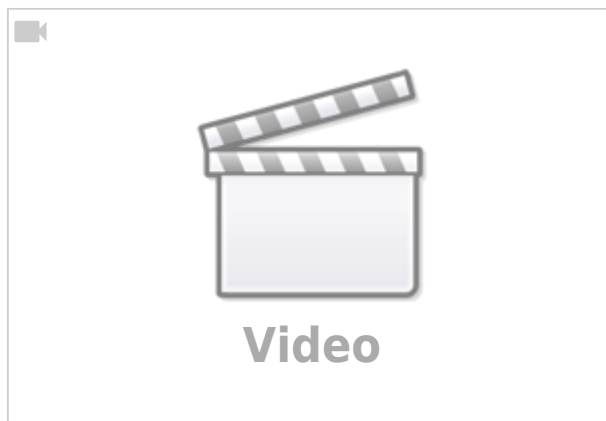
Otros



Videos

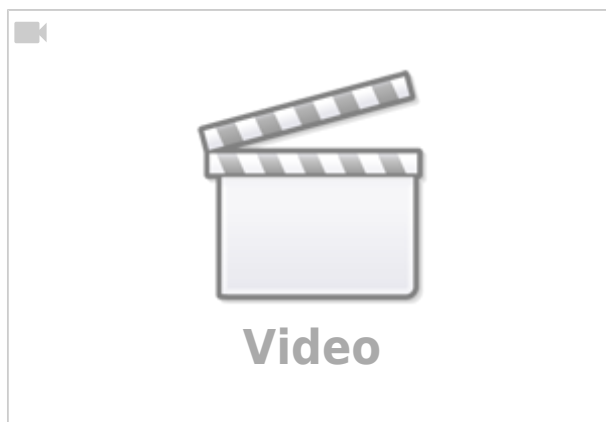
1

[Entradas y Salidas \(I\) \(28m 35s\)](#)



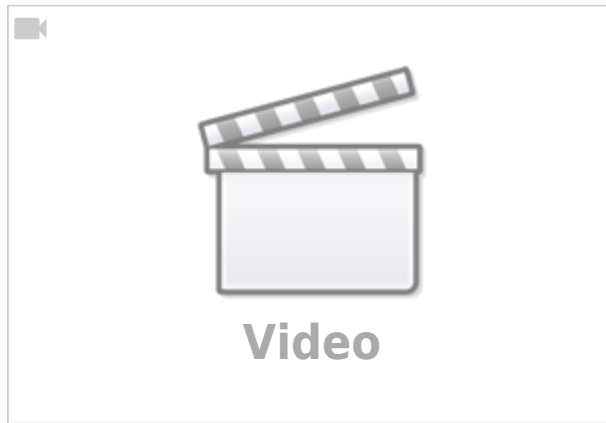
2

[Entradas y Salidas \(II\) \(42m 53s\)](#)



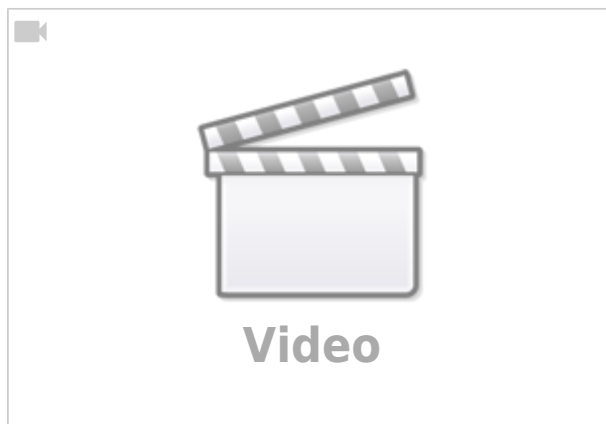
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[Entradas y salidas virtuales en Robotware 6 \(14m 34s\)](#)



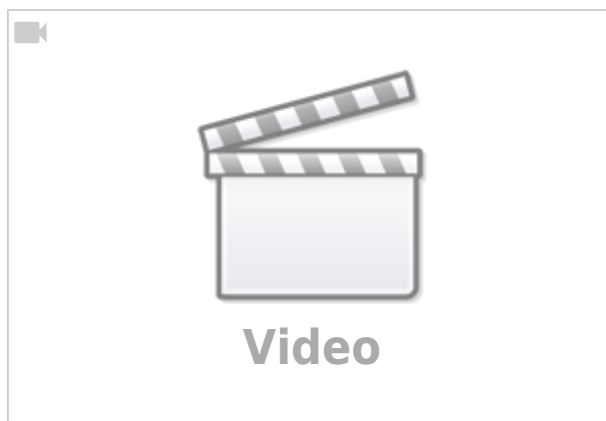
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[Detener o reanudar el movimiento de un robot con entradas digitales \(4m 01s\)](#)



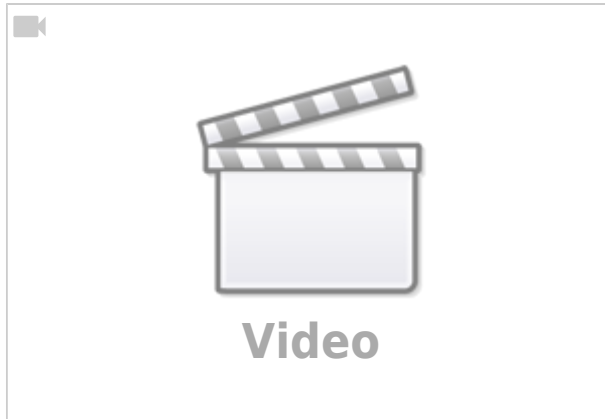
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[Propuesta de actividad: Paletizado \(0m 43s\)](#)

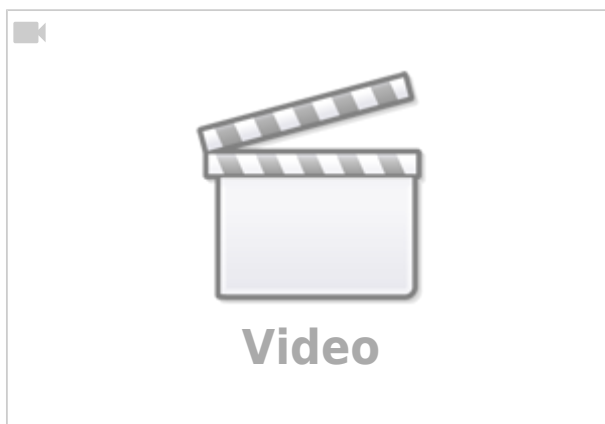


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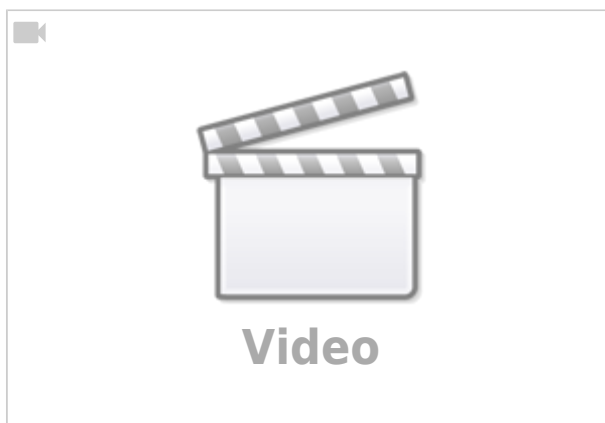
[Iniciación al uso de Smart Components \(34m 03s\)](#)



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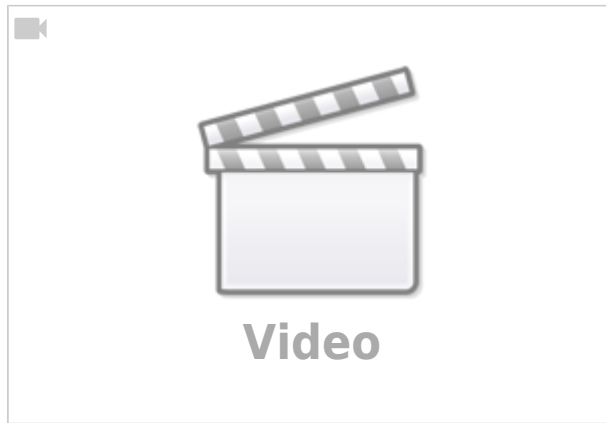
[Kit de Smart Components para RobotStudio \(11m 58s\)](#)

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[Comunicación con WinCC Flexible mediante OPC Server \(51m 40s\)](#)

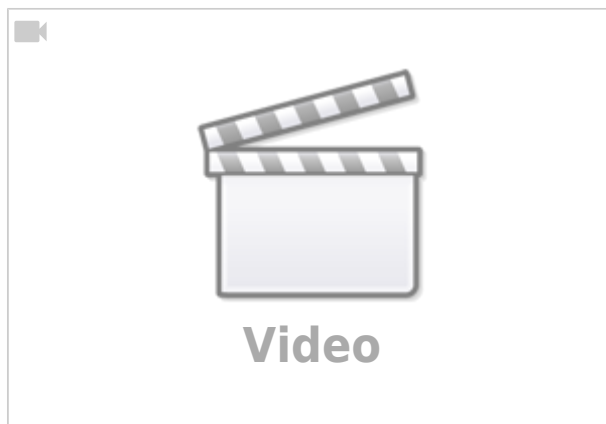
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[Proyecto \(1\): Programando y copiando trayectorias \(19m 12s\)](#)



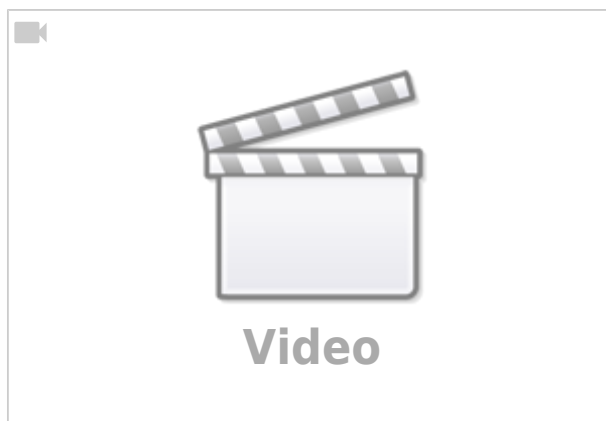
10

[Proyecto \(2\): Uso de If-Then, For, CallByVar, TPreadNumb \(21m 36s\)](#)



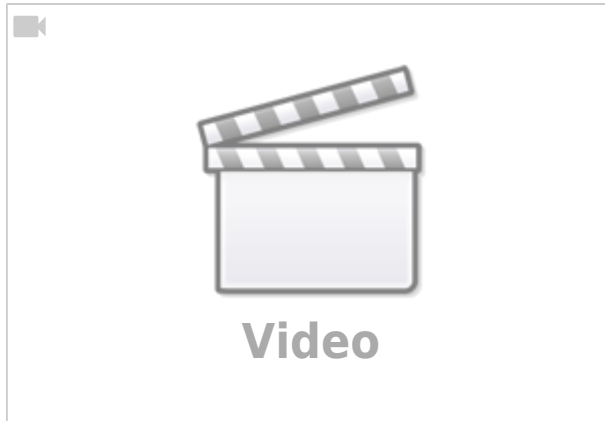
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[Proyecto \(3\): Activar salidas digitales con SetDO \(22m 05s\)](#)



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[Proyecto \(4\): HMI en FlexPendant con ScreenMaker \(42m 45s\)](#)



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